

BFS & DFS

Kuan-Yu Chen (陳冠宇)

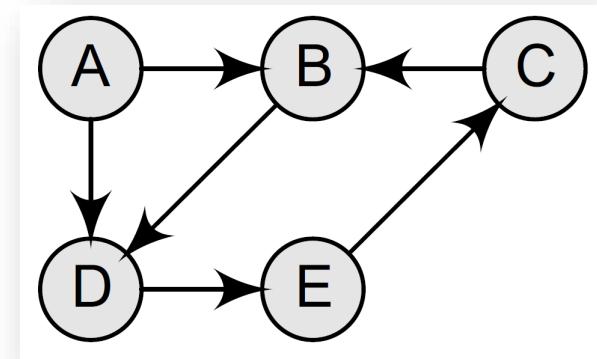
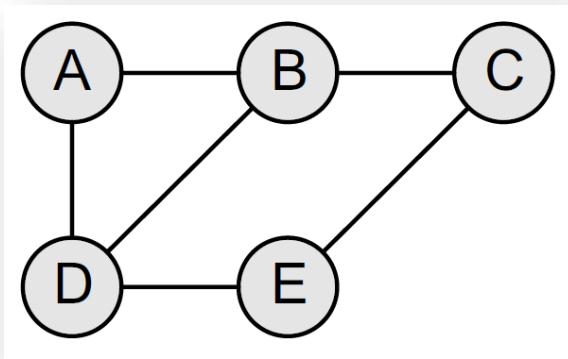
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Levenshtein Distance

- Word error rate (WER) is a common metric of the performance of a speech recognition or machine translation system
 - If the answer is “今天 天氣 很好”
 - “今天 天晴 很好”
Substitution Error
 - “今天 天氣 是 很好”
Insertion Error
 - “今天 很好”
Deletion Error
 - The formulation of word error rate is $WER = \frac{S+D+I}{|Ref|}$

Undirected & Directed Graphs

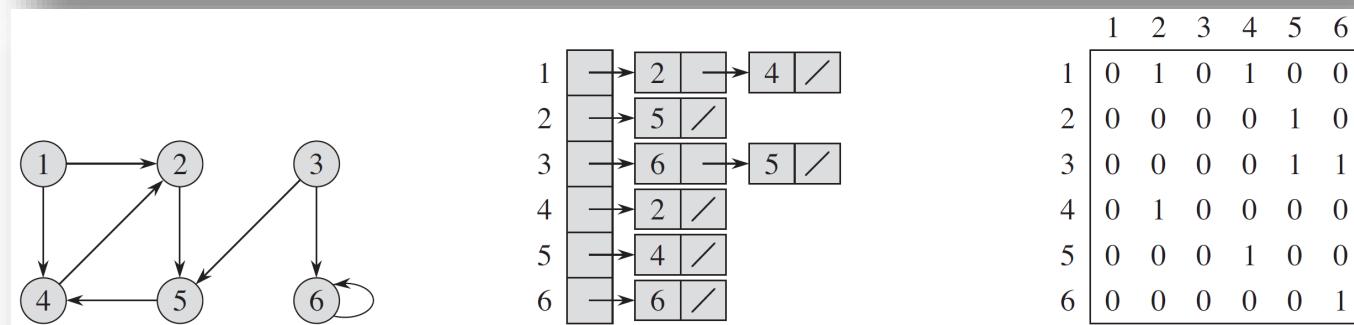
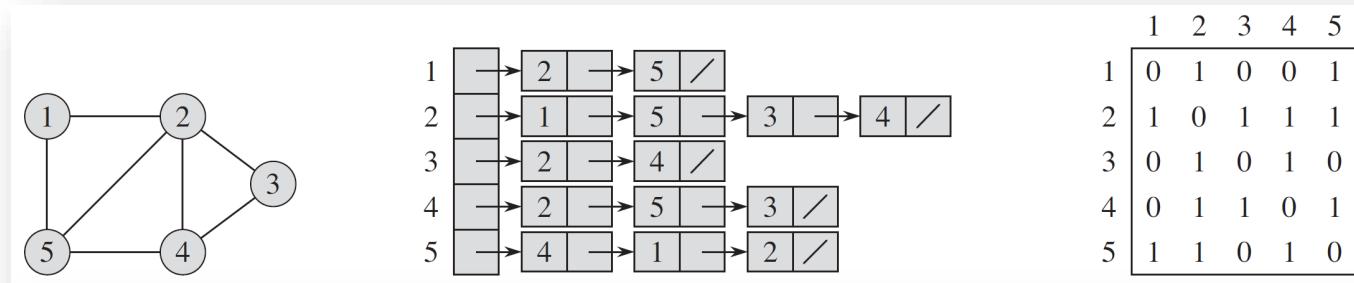
- A graph G is defined as an ordered set (V, E) , where $V(G)$ represents the set of vertices and $E(G)$ represents the edges
 - For a given undirected graph with $V(G) = \{A, B, C, D, E\}$ and $E(G) = \{(A, B), (B, C), (A, D), (B, D), (D, E), (C, E)\}$
 - Five vertices or nodes and six edges in the graph



- For a given directed graph, the edge (A, B) is said to initiate from node A (also known as initial node) and terminate at node B (terminal node)

Graph Representations

- There are two standard ways to represent a graph $G = (V, E)$
 - Adjacency list
 - **Sparse** graph
 - $|E|$ is much less than $|V|^2$
 - Adjacency matrix
 - **Dense** graph
 - $|E|$ is close to $|V|^2$

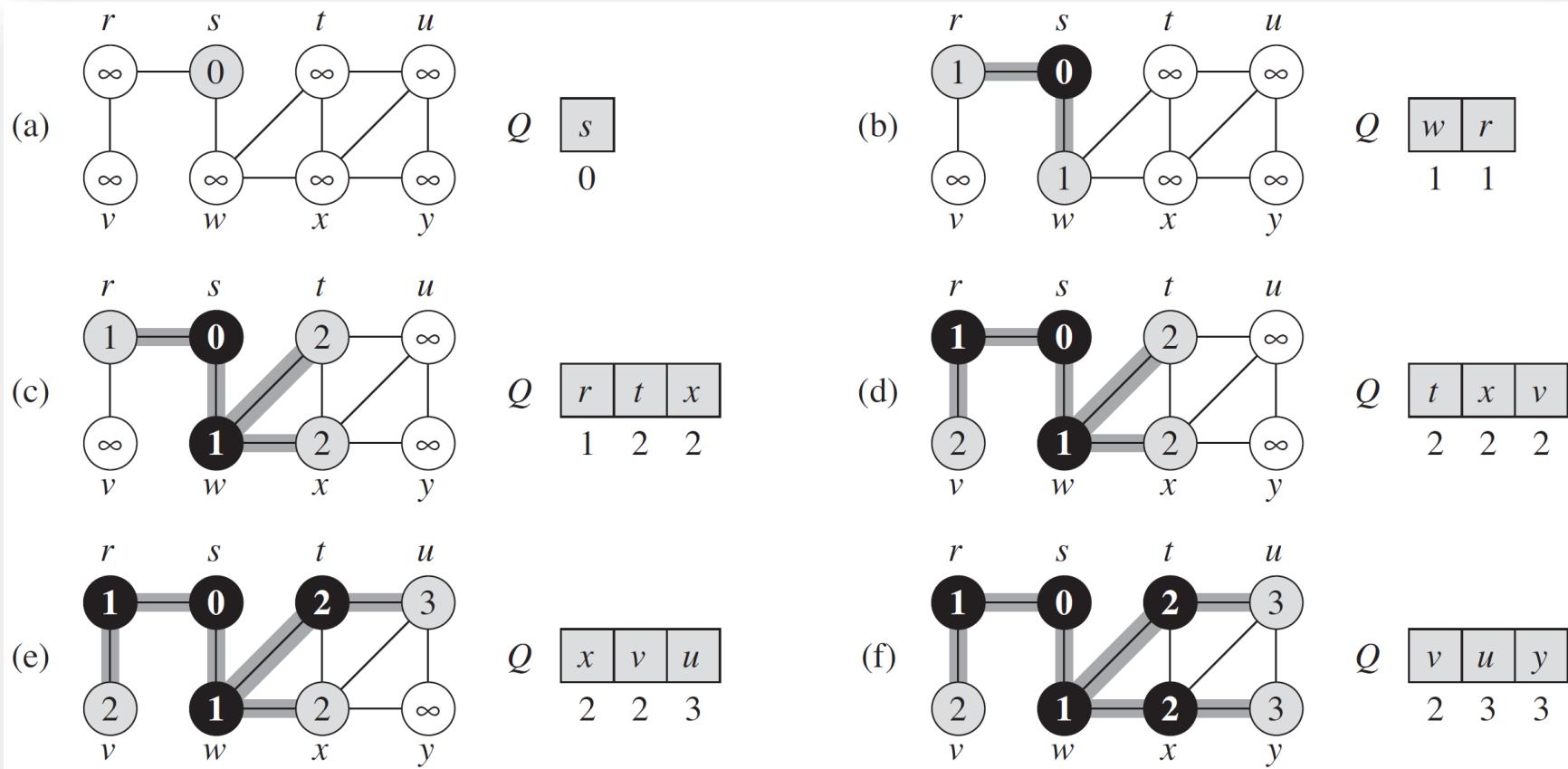


Breadth-first Search.

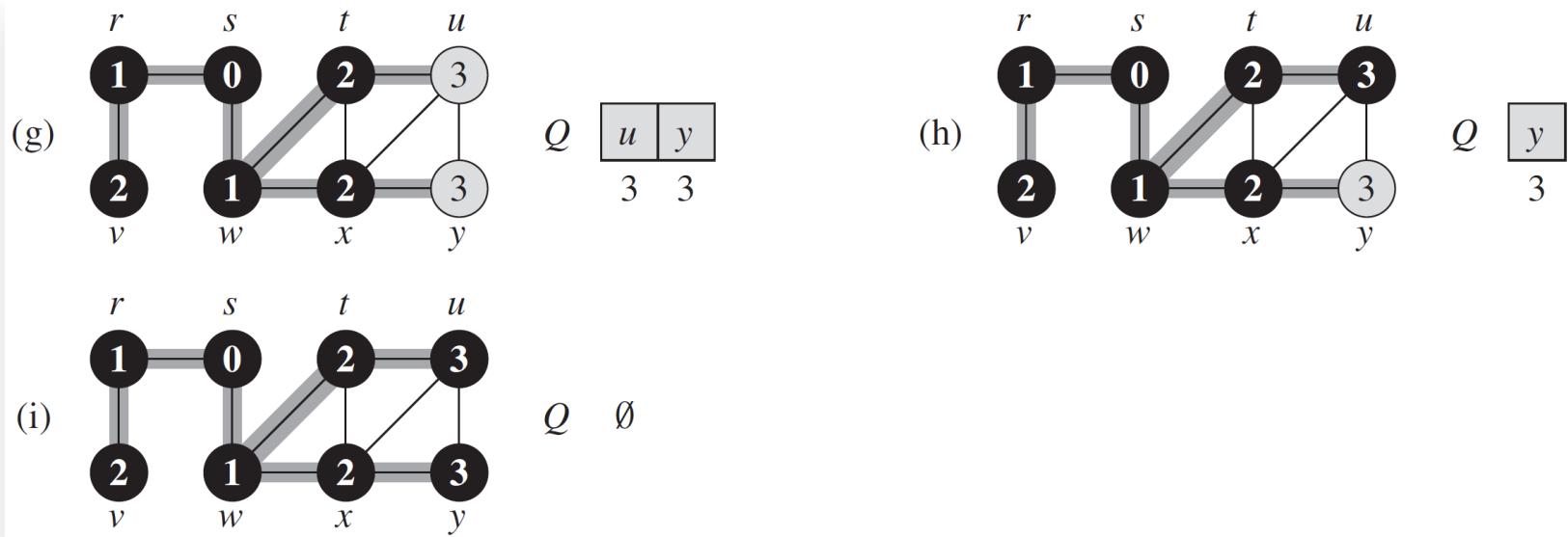
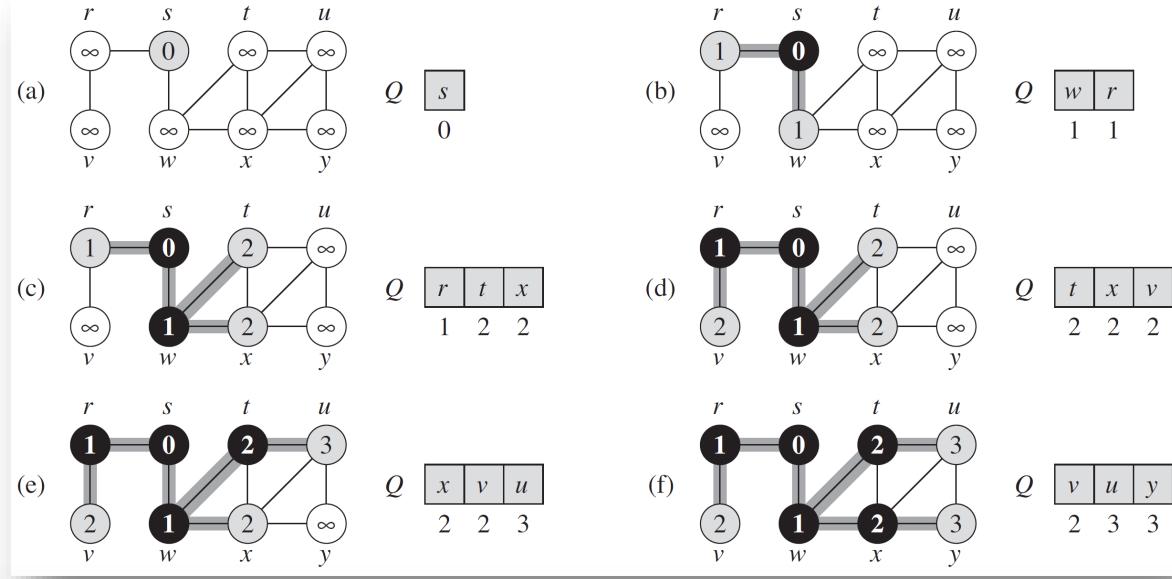
- **Breadth-first search** is one of the simplest algorithms for searching a graph
 - Given a graph $G = (V, E)$ and a distinguished **source** vertex s
 - Breadth-first search systematically explores the edges of G to “discover” every vertex that is reachable from s

```
BFS( $G, s$ )
1  for each vertex  $u \in G.V - \{s\}$ 
2     $u.color = \text{WHITE}$ 
3     $u.d = \infty$ 
4     $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11    $u = \text{DEQUEUE}(Q)$ 
12   for each  $v \in G.\text{Adj}[u]$ 
13     if  $v.color == \text{WHITE}$ 
14        $v.color = \text{GRAY}$ 
15        $v.d = u.d + 1$ 
16        $v.\pi = u$ 
17       ENQUEUE( $Q, v$ )
18    $u.color = \text{BLACK}$ 
```

Breadth-first Search..



Breadth-first Search...



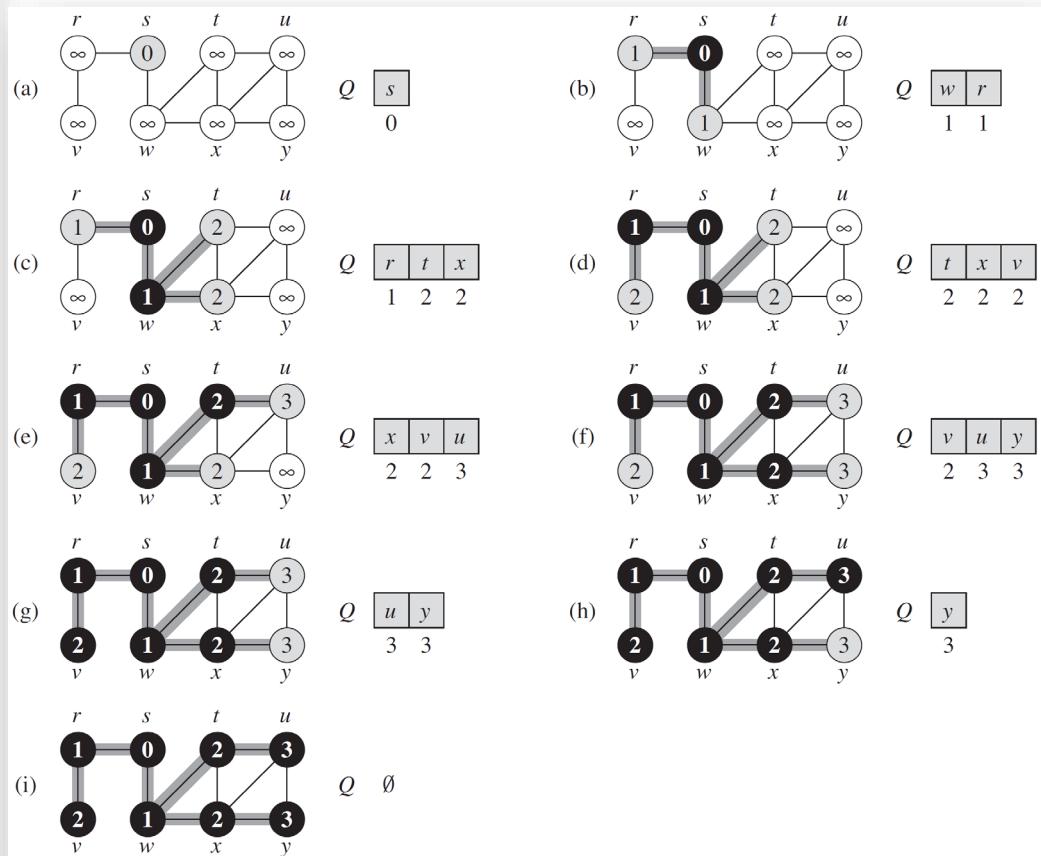
Breadth-first Search....

$\text{BFS}(G, s)$

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Depth-first Search.

- The strategy followed by depth-first search is, as its name implies, to search “deeper” in the graph whenever possible

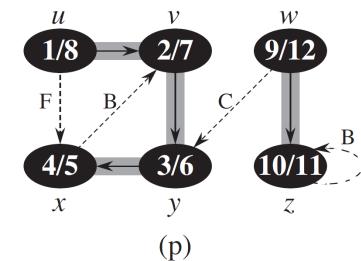
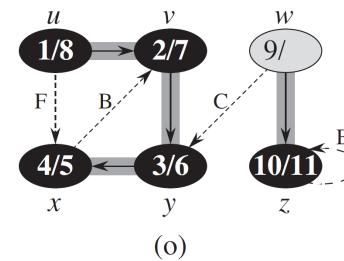
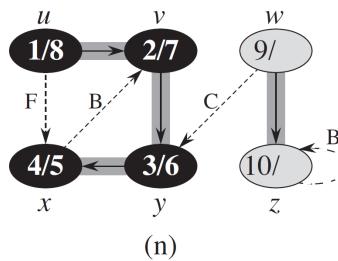
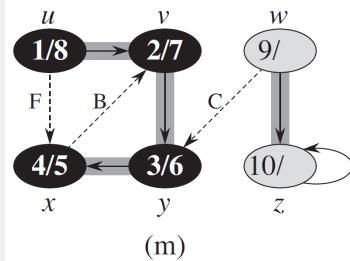
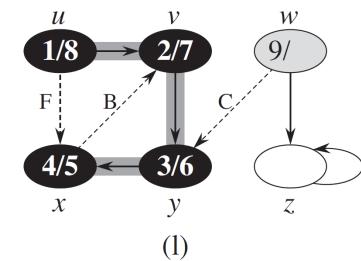
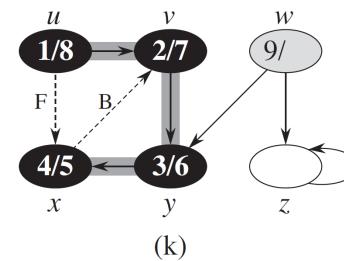
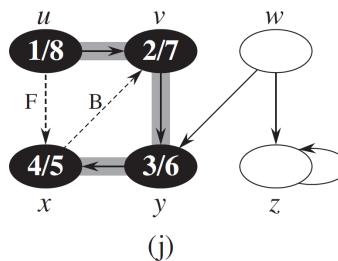
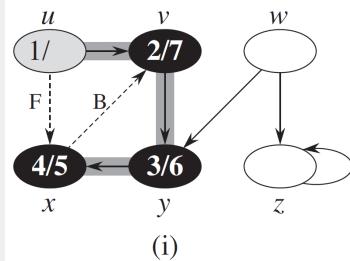
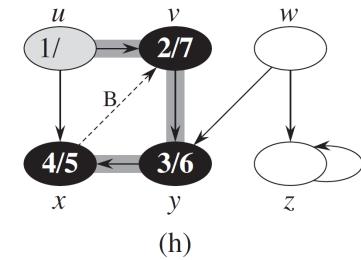
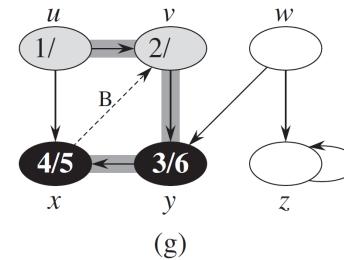
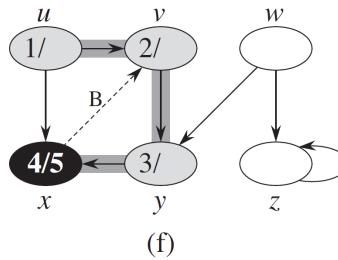
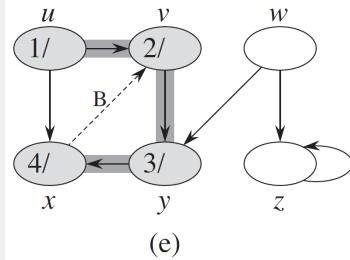
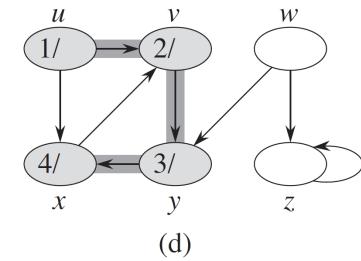
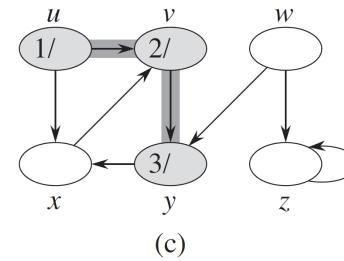
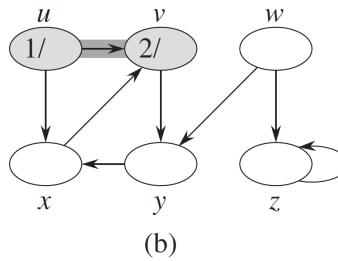
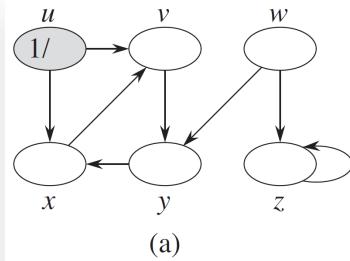
DFS(G)

```
1  for each vertex  $u \in G.V$ 
2       $u.color = \text{WHITE}$ 
3       $u.\pi = \text{NIL}$ 
4       $time = 0$ 
5  for each vertex  $u \in G.V$ 
6      if  $u.color == \text{WHITE}$ 
7          DFS-VISIT( $G, u$ )
```

DFS-VISIT(G, u)

```
1   $time = time + 1$            // white vertex  $u$  has just been discovered
2   $u.d = time$ 
3   $u.color = \text{GRAY}$ 
4  for each  $v \in G.Adj[u]$       // explore edge  $(u, v)$ 
5      if  $v.color == \text{WHITE}$ 
6           $v.\pi = u$ 
7          DFS-VISIT( $G, v$ )
8   $u.color = \text{BLACK}$            // blacken  $u$ ; it is finished
9   $time = time + 1$ 
10  $u.f = time$ 
```

Depth-first Search..



Depth-first Search...

DFS(G)

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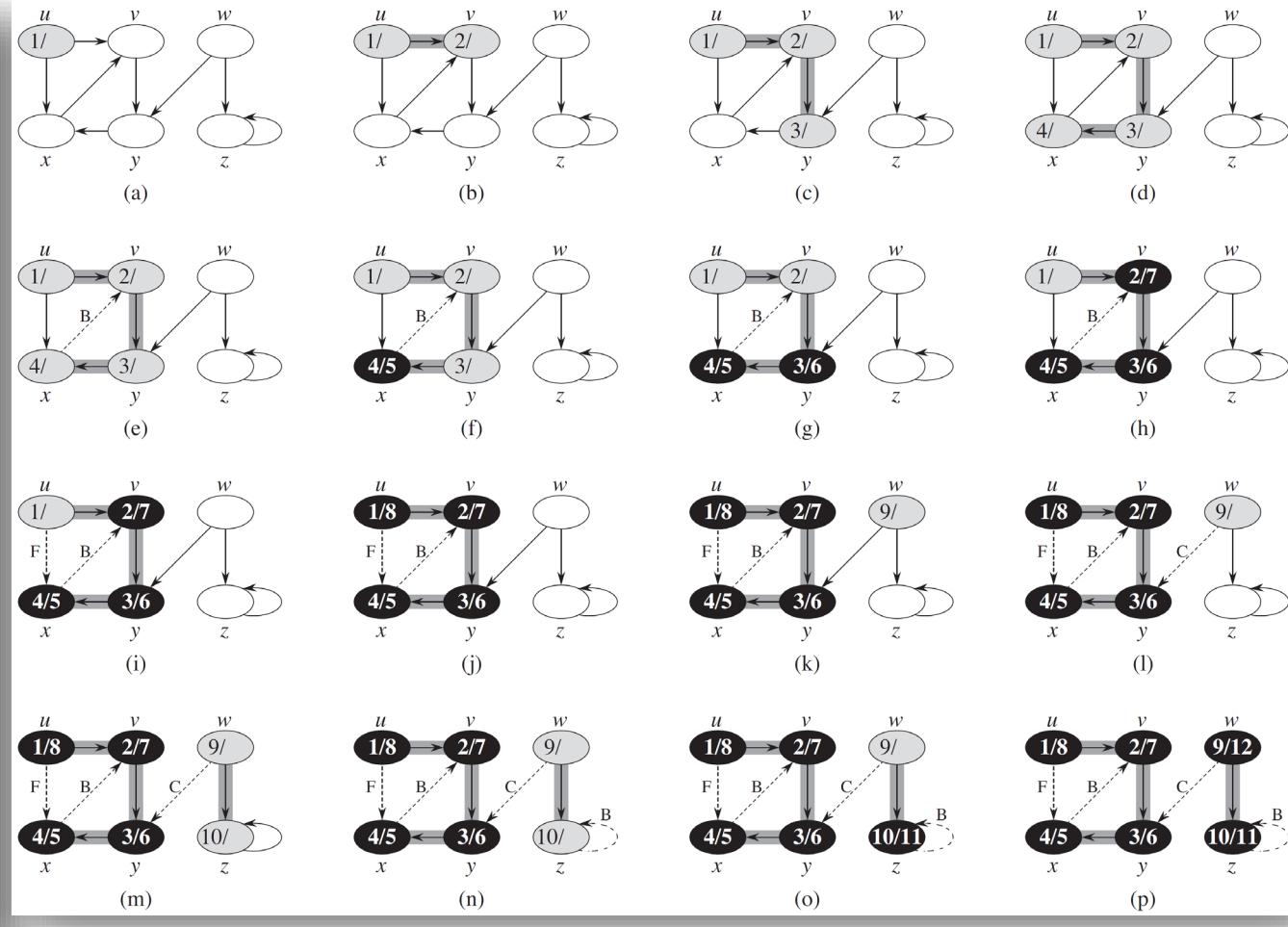
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DFS-VISIT(G, u)

```

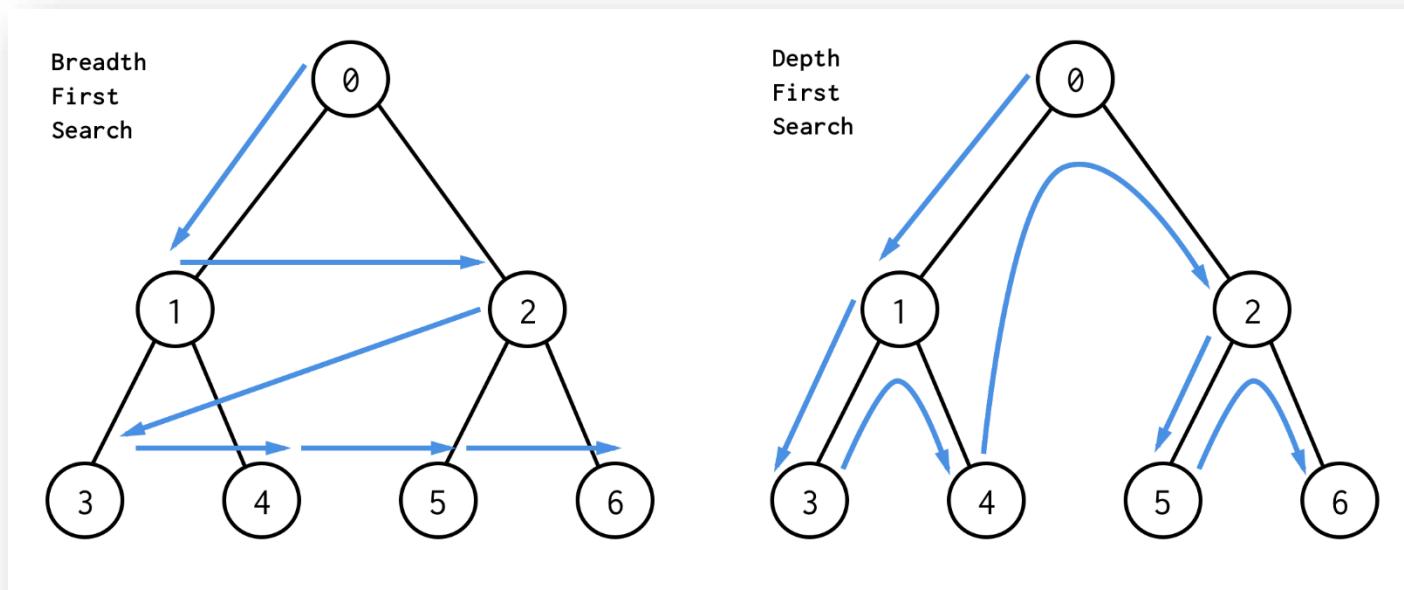
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```



BFS & DFS

- Breadth-first search
 - BFS uses a **queue** as an auxiliary data structure to store nodes for further processing
- Depth-first search
 - DFS uses a **stack** to store nodes for further processing



Questions?



kychen@mail.ntust.edu.tw